ISHIKAA LUNAWAT

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Education

Stanford University, CA

Master of Science in Electrical Engineering (Software and Hardware Systems – Machine Learning) Coursework: Sensorimotor learning for Embodied Agents, Principles of Robot Autonomy, Artificial Intelligence

National Institute of Technology Tiruchirappalli, India Bachelors of Technology in Electrical and Electronics Engineering Coursework: Machine Learning and Deep Learning, Industrial Automation, Control Systems

Teaching: Machine Learning and Deep Learning MOOCs: Deep Learning Specialization, Modern Robotics (Course 1), Machine Learning A-Z

Technical Skills

Programming Languages: Python, C++, C

Tools & Frameworks: PyTorch, Tensorflow, OpenCV, PyBullet, Open3D, Keras, Gazebo, Scikit learn, OpenGL Software: MATLAB, Visual Studio Code, Git, Anaconda, ROS

Relevant Experience

Robot Perception and 3D Vision Intern

Intelligent Autonomous System Laboratory

- Developed a novel semi-implicit **neural surface rendering** network to learn 3D scene representation and generate 6DoF grasp poses, achieving high grasp success rate of 81.80% for 'pile' scenes and 90.48% for 'packed' scenes
- Conducted method evaluation through **Pybullet simulations** and real-robot experiments on the **TIAGo++** robot equipped with Robotiq Gripper and a ZED2 Stereo (depth) camera, performing with a high success rate of $\sim 90\%$
- Co-authored and presented accepted paper at CVPR 2023 workshop on 3D Vision and Robotics, spotlight talk presentation in collaboration with other members of research group

Machine Learning Intern

Omnyk Inc.

- Optimized sleep-stage classification by integrating squeeze-and-excite blocks, resulting in a remarkable 73% accuracy on processed interbeat interval data compared to current deep learning methods
- Led a team of 3 to plan and manage the execution of research models and maintain the Git organization repository for streamlined workflow
- Performed sleep quality analysis in collaboration with team of 7 members for 10+ patients and created heart health reports with visualizations for patients diagnosed with cardiovascular problems

Computer Vision – Gait Recognition Intern

Pattern Recognition Laboratory

- Examined current gait recognition methods to understand effect of static occlusions and performed extensive literature review for improvement of vision-based models
- Innovated a novel **spatio-temporal** models for impainting occluded frames using 3D convolutions and embedding lavers on the TUM-IITKGP dataset
- Boosted accuracy by 20% through pioneering a **3D** Convolution and Conv-LSTM model with key-pose embedding layers, surpassing frame averaging methods

Projects

Image-Sensor Fusion for Sign Language Detection (GISiL)

- Developed a novel latent space translation model for classifying noisy sensor inputs to ASL alphabet by using image-sensor feature fusion, resulting in a 85.7% improvement over naive classification
- Spearheaded a team of 3 integrating different modules to win runner's up at Sangam Hackathon 2021
- Contributed to writing and publishing a short paper as a first author at Medical Imaging and Deep Learning **Conference 2022** and qualified for poster presentation among 125 short papers

Publications

NeuGraspNet: 6-DoF Grasp Detection in Clutter with Neural Surface Rendering | Link Learning Any-View 6DoF Robotic Grasping in Cluttered Scenes | Link SIHeDA-Net: Sensor to Image Heterogeneous Domain Adaptation Network | Link

June 2023 (Under review) July 2022

San Jose, CA (remote)

2023 - Present

2019 - 2023

GPA: 9.58/10

- August 2022 March 2023

May 2022 - July 2023

TU Darmstadt, Germany

- May 2021 July 2021 IIT BHU, India

December 2020 – March 2021